# Kvaser USBcan R v2 User's Guide



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## 1 About this manual

This manual is intended for Kvaser USBcan R v2 users. This document contains a description of the hardware's properties and general instructions for connecting the device to a computer.



### 2 Introduction

This section will describe the functions and features of the Kvaser USBcan R v2.

### 2.1 Welcome to Kvaser USBcan R v2



Figure 1: Kvaser USBcan R v2

Kvaser USBcan R v2 is a reliable low cost product. In hostile environments wheredust and water are the norm, the IP65 rated housing assures reliable protection. With a time stamp precision of 100 microseconds it handles transmission and reception of standard and extended CAN messages on the bus. It is compatible with applications that use Kvaser's CANlib.

This guide applies to Kvaser USBcan R v2 devices listed in Table 1.

Device	Product Number
Kvaser USBcan R v2 2xHS	73-30130-00920-2

Table 1: Kvaser USBcan R v2 devices and their EAN numbers.



### 2.2 Major features

- USB CAN interface.
- IP65 rated lightweight aluminum housing.
- Quick and easy plug-and-play installation.
- Supports both 11-bit (CAN 2.0A) and 29-bit (CAN 2.0B active) identifiers.
- 100% compatible with applications written for other Kvaser CAN hardware with Kvaser CANlib.
- High-speed CAN connection (compliant with ISO 11898-2), up to 1 Mbit/s.
- Fully compatible with J1939, CANopen, NMEA 2000 ® and DeviceNet.
- Simultaneous operation of multiple devices.

### 2.3 Additional software and documentation

The Kvaser CANlib SDK includes everything you need in order to develop software applications interacting with Kvaser CAN and LIN hardware. The SDK contains full documentation and many sample programs, written in C, C++, C#, Delphi, Python and Visual Basic. Kvaser CAN and LIN hardware is built around the same commonsoftware API. Applications developed using one device type will run without modification on other device types.

The latest versions of documentation, software and drivers can be downloaded forfree at www.kvaser.com/download.



### 3 Kvaser USBcan R v2 hardware

In this section you can read more about the CAN channels, power supply and LED indicators.

#### 3.1 Hardware installation

For the Kvaser USBcan R v2 to communicate with the host computer, a compatible version of the Kvaser driver and firmware must be installed.

After the driver has been installed on the host computer, the firmware may then bedownloaded and installed on the Kvaser USBcan R v2.

The latest version of the driver and firmware can be downloaded from www.kvaser.com/download.

The driver is installed by running the file kvaser\_drivers\_setup.exe.

The Kvaser USBcan R v2 may be inserted in any free USB socket on the host computer. You do not need to switch the power off before inserting or removing the device.

For information on how to upgrade the firmware, see Section 4.4, Updating the firmware, on Page 11.

### 3.2 USB connector

The Kvaser USBcan R v2 has a standard USB type "A" connector.



Figure 2: A standard USB type "A" connector.

### 3.3 CAN channels

The Kvaser USBcan R v2 has two CAN Hi-Speed channels with 9-pin D-SUB CAN connectors (see Figure 3 on Page 8). See Section 4.2, CAN connectors, on Page 10 for pinout information.



Figure 3: CAN connectors on Kvaser USBcan R v2 2xHS

### 3.4 Power supply

The Kvaser USBcan R v2 is powered from the USB port.

### 3.5 LED Indicators

The Kvaser USBcan R v2 has three LEDs as shown in Figure 4. Their functions are shown in Table 2 on Page 9.



Figure 4: LEDs on the Kvaser USBcan R v2.

LED	Function	Description
PWR (Green)	Power	Steady light when unit is powered and working.
	USB configuration	Blinking once every three seconds when something is wrong with the USB connection.
	Firmware	2 Hz flash if something is wrong with the firmware configuration.
CAN 1 (Yellow)	CAN RxTx	Status for CAN channel 1.
CAN 2 (Yellow)	CAN RxTx	Status for CAN channel 2.

Table 2: LEDs on the Kvaser USBcan R v2.

## 3.6 Troubleshooting

Use "Kvaser Device Guide" in the Control Panel to verify that the computer can communicate with the Kvaser USBcan R v2. If the firmware version shown is allzeros, there are communication problems. If the LEDs are not flashing or do notlight up at all, check the power supply.



# 4 Appendices

In this section you will find technical information about the Kvaser USBcan R v2and its connectors.

### 4.1 Technical data

In Table 3 below you will find the Kvaser USBcan R v2's technical specifications.

CAN Channels	2 (No galvanic isolation between CAN channels.)
CAN Transceivers	TJA1051T (Compliant with ISO 11898-2)
CAN Controller	Built into the processor
Galvanic isolation	Yes
CAN Bit Rate	50 kbit/s to 1 Mbit/s
Time stamp resolution	100 μs
Max message rate	15000 msg/s per channel
Error Frame Detection	Yes
Error Frame Generation	No
Silent mode	No
Kvaser CANtegrity	No
Host interface	USB Hi-Speed
Host OS	Windows (7 or later), Linux.
Power consumption	Typical 132 mA
Hardware configuration	Done by software (Plug & Play).
Dimensions	30 x 200 x 17 mm for body incl. strain relief
Weight	176 g
Operating temperature	−40 °C to +70 °C
Storage temperature	-40 °C to +85 °C
Relative humidity	0 % to 85 % (non-condensing.)
IP Rating	IP65

Table 3: Technical Specifications.

### 4.2 CAN connectors

Kvaser USBcan R v2 devices that use the 9-pin D-SUB connector (see Figure 5 on Page 11) have the pinning described in Table 4 on Page 11.



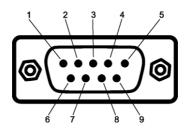


Figure 5: The D-SUB 9 connector pin numbers

D-SUB pin number	Function
1	Not connected
2	CAN_L
3	GND
4	Not connected
5	Shield
6	Not connected
7	CAN_H
8	Not connected
9	Not connected

Table 4: Configuration of the 9-pin D-SUB

### 4.3 CAN bus termination

Every CAN bus must be terminated with a 120 Ohm resistor at each end of thebus. The Kvaser USBcan R v2 does not contain any CAN bus termination, because their inclusion could cause severe disturbance in a system which is already correctly terminated.

For laboratory or testing use, the exact value of the termination resistors is not always critical. Sometimes a single terminator is sufficient. For production, propertermination is essential. If you see error frames on the bus, you should check the termination.



To save yourself a lot of trouble, always terminate the CANbus properly.

### 4.4 Updating the firmware

For the Kvaser USBcan R v2 to communicate with the host computer, compatible versions of the Kvaser CANlib (including driver) and firmware must be installed.

The latest versions of firmware and drivers can be downloaded for free at www.kvaser.com/download.



Connect the Kvaser USBcan R v2 to your host computer with the USB cable. Startthe update.exe application. A window opens where you should see the device listed if correctly connected to your host computer. Select the device to update and click the Next button. Read the Release Notes carefully.

Click on the Start Upgrade button to start programming. Programming takes approximately 30 s. The progress is displayed on the screen.

If you see any error messages, try to disconnect and reconnect the device, andthen perform the operation again.

To verify that the firmware has been updated, open "Kvaser Device Guide" in Control Panel. Select "Kvaser USBcan R v2" in the tree view to the left, and clickon the channel. The firmware revision information appears in the right half of thewindow.



# 5 Disposal and Recycling Information



When this product reaches its end of life, please dispose of it according to your local environmental laws and guidelines.

For information about Kvaser's recycling programs, visit: https://www.kvaser.com/en/kvaser/recycling-policy.html



## Legal acknowledgements

### **Usage warning**



#### WARNING FOR ALL USERS

WARNING! - YOUR USE OF THIS DEVICE MUST BE DONE WITH CAUTION AND A FULL UNDERSTANDING OF THE RISKS!

THIS WARNING IS PRESENTED TO INFORM YOU THAT THE OPERATION OF THIS DEVICE MAY BE DANGEROUS, YOUR ACTIONS CAN INFLUENCE THE BEHAVIOR OF A CAN-BASED DISTRIBUTED EMBEDDED SYSTEM, AND DEPENDING ON THE APPLICATION, THE CONSEQUENCES OF YOUR IMPROPER ACTIONS COULD CAUSE SERIOUS OPERATIONAL MALFUNCTION, LOSS OF INFORMATION, DAMAGE TO EQUIPMENT, AND PHYSICAL INJURY TO YOURSELF AND OTHERS. A POTENTIALLY HAZARDOUS OPERATING CONDITION IS PRESENT WHEN THE FOLLOWING TWO CONDITIONS ARE CONCURRENTLY TRUE: THE PRODUCT IS PHYSICALLY INTERCONNECTED TO A REAL DISTRIBUTED EMBEDDED SYSTEM; AND THE FUNCTIONS AND OPERATIONS OF THE REAL DISTRIBUTED EMBEDDED SYSTEM ARE CONTROLLABLE OR INFLUENCED BY THE USE OF THE CAN NETWORK. A POTENTIALLY HAZARDOUS OPERATING CONDITION MAY RESULT FROM THE ACTIVITY OR NON-ACTIVITY OF SOME DISTRIBUTED EMBEDDED SYSTEM FUNCTIONS AND OPERATIONS, WHICH MAY RESULT IN SERIOUS PHYSICAL HARM OR DEATH OR CAUSE DAMAGE TO EQUIPMENT, DEVICES, OR THE SURROUNDINGENVIRONMENT.

WITH THIS DEVICE, YOU MAY POTENTIALLY:

- CAUSE A CHANGE IN THE OPERATION OF THE SYSTEM, MODULE, DEVICE, CIRCUIT, OR OUTPUT.
- TURN ON OR ACTIVATE A MODULE, DEVICE, CIRCUIT, OUTPUT, OR FUNCTION.
- TURN OFF OR DEACTIVATE A MODULE, DEVICE, CIRCUIT, OUTPUT, OR
- INHIBIT, TURN OFF, OR DEACTIVATE NORMAL OPERATION.
- MODIFY THE BEHAVIOR OF A DISTRIBUTED PRODUCT. ACTIVATE
- AN UNINTENDED OPERATION.
- PLACE THE SYSTEM, MODULE, DEVICE, CIRCUIT, OR OUTPUT INTO AN UNINTENDED MODE.

#### ONLY THOSE PERSONS WHO:

- (A) ARE PROPERLY TRAINED AND QUALIFIED WITH RESPECT TO THE USE OF THE
- (B) UNDERSTAND THE WARNINGS ABOVE, AND
- (C) UNDERSTAND HOW THIS DEVICE INTERACTS WITH AND IMPACTS THE FUNCTION AND SAFETY OF OTHER PRODUCTS IN A DISTRIBUTED SYSTEM AND THE APPLICATION FOR WHICH THIS DEVICE WILL BE APPLIED, MAY USE THE DEVICE.

PLEASE NOTE THAT YOU CAN INTEGRATE THIS PRODUCT AS A SUBSYSTEM INTO HIGHER-LEVEL SYSTEMS. IN CASE YOU DO SO, KVASER AB HEREBY DECLARES THAT KVASER AB'S WARRANTY SHALL BE LIMITED TO THE CORRECTION OF DEFECTS, AND KVASER AB HEREBY EXPRESSLY DISCLAIMS ANY LIABILITY OVER AND ABOVE THE REFUNDING OF THE PRICE PAID FOR THIS DEVICE, SINCE KVASER AB DOES NOT HAVE ANY INFLUENCE ON THE IMPLEMENTATIONS OF THE HIGHER-LEVEL SYSTEM, WHICH MAY BE DEFECTIVE.



#### **6.2 EU Regulatory Compliance**



#### EU Declaration of Conformity (DoC)

We

Company Name: Kvaser AB City: Mölndal

+46 31 886344 Aminogatan 25 Telephone number: Postal address: 431 53 sales@kvaser.com Postcode: E-mail address:

 $\ declare\ that\ the\ DoC\ is\ is sued\ under\ our\ sole\ responsibility\ and\ belongs\ to\ the\ following\ product:$ 

Kvaser USBcan R v2

Object of the declaration (identification of apparatus allowing traceability):

Product: Kvaser USBcan R v2 Type: 73-30130-00920-2

The object of the declaration described above is in conformity with the relevant Union harmonisationlegislation:

Electromagnetic Compatibility (EMC) Directive 2014/30/EU (Art. 6)

RoHS recast Directive 2011/65/EU (Art. 4.1)

The following harmonised standards and technical specifications have been applied (title, date of standard/specification):

EN 55024 (2010) EN 55032 (2012)

EN 61000-6-3 (2007 + A1:2011) EN 50581 (2012)

Signed for and on behalf of:

2019-12-05 Molndal

Place of issue Claes Haglund, Supply Chain and Quality director

## **6.3** FCC Regulatory Compliance



#### Federal Communications Commission (FCC) Compliance Information Statement

### **IDENTIFICATION OBJECT:**

Product: Kvaser USBcan R v2 Type: 73-30130-00920-2

### APPLICABLE COMPLIANCE STATEMENTS:

CFR Title 47 Part 15 §15.107, §15.109

This device complies with part 15 of the FCC Rules.

Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference, and
- (2) this device must accept any interference received, including interference that may cause undesired operation.

### **RESPONSIBLE PARTY (IN USA) NAME:**

Kvaser Inc.

23881 Via Fabricante, Suite 503 Mission Viejo, CA 92691

Internet contact: support@kvaser.com



### 6.4 Patents, Copyrights and Trademarks

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DeviceNet is a trademark of Open DeviceNet Vendor Association, Inc.

NMEA 2000 is the registered trademark of the National Marine Electronics Association, Inc.

For information about Kvaser related CAN patents, see www.kvaser.com/patent.



# 7 Document Revision History

Version history for document UG\_98185\_usbcan\_r\_v2:

Revision	Date	Changes
1.0	2017-01-18	Initial version
2.0	2017-08-25	Updated EU Declaration of Conformity
2.1	2018-01-29	"Kvaser Device Guide" has replaced "Kvaser
		Hardware"
2.2	2018-05-07	Minor textual changes
2.3	2018-08-28	Minor textual changes
3.0	2018-10-15	Updated EU Regulatory Compliance
3.1	2019-02-11	Minor textual changes
3.2	2019-08-09	Minor textual changes, Url protocol updated
3.3	2020-01-27	Added sdoc
3.4	2020-08-27	Updated supported OS
3.5	2022-04-01	Minor textual changes, added galvanic isolation info to
		Technical data table.

